Computer Programming 9/10 Assignment # 2 – *Reading data from sensors*

Bumper Vehicle



Program your vehicle to:

Drive forward *and* when it bumps into something (head-on) it will: Move backwards, turn 90 degrees *and* then begin moving forward again. Have the program run until you stop it.

Steps to completion:

- 1. Build and attach a "bumper" for your vehicle using a touch sensor(s).
- 2. Set up a touch sensor using: Robot \rightarrow Motor and Sensor Setup
- 3. Write code for the task above.

Marking Scheme:

Working vehicle 5 marks

Print out of Program **5 marks** (neatly spaced, includes comments, your name in comments)

